

Alternating Minimization Algorithms for Graph Regularized Tensor Completion

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What is a tensor

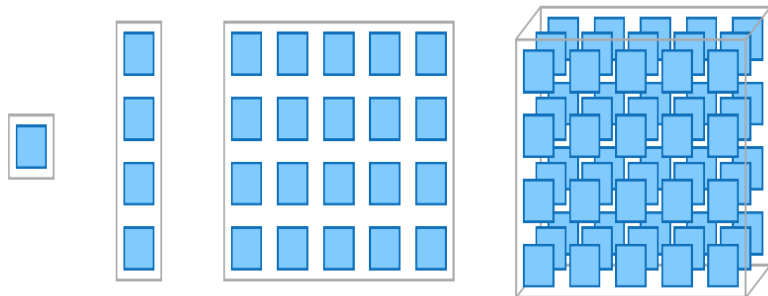


Figure : $x \in \mathbb{R}, \mathbf{x} \in \mathbb{R}^4, \mathbf{X} \in \mathbb{R}^{4 \times 5}, \mathcal{X} \in \mathbb{R}^{4 \times 5 \times 3}$

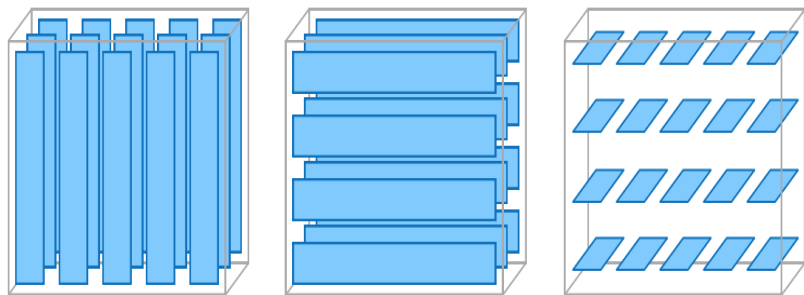


Figure : Column, row, and tube fibers of a order-3 tensor

Multiway Data

- ▶ **Psychometrics:** individual \times variable \times time
- ▶ **Time-series analysis:** time \times variable \times lag
- ▶ **Neuroscience:** electrodes \times time \times frequency
- ▶ **Social networks:** users \times keywords \times time
- ▶ **Facial image:** people \times view \times illumination \times expression \times pixels
- ▶ **Atmospheric science:** location \times variable \times time \times observation

Tensor Completion

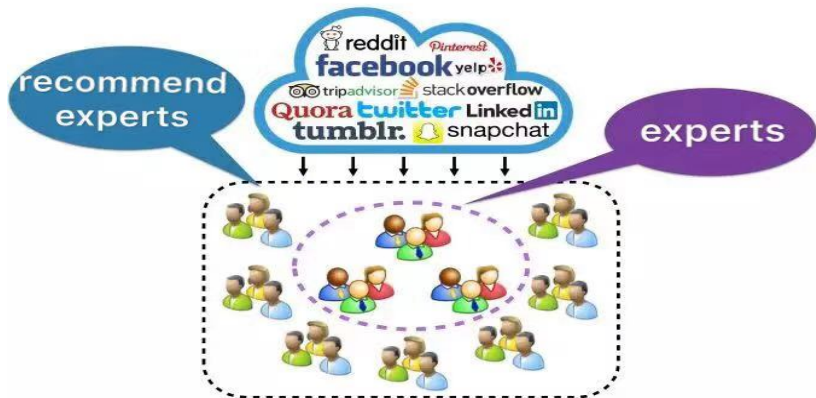
Recommender System

Item

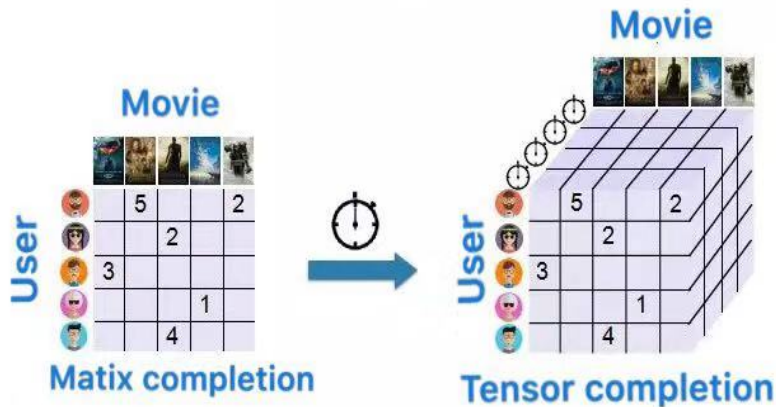


Social media





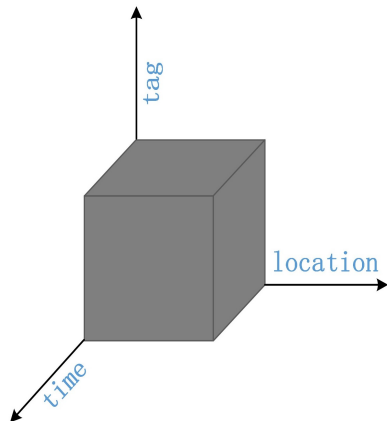
Movie Rating



Spatio-Temporal Data

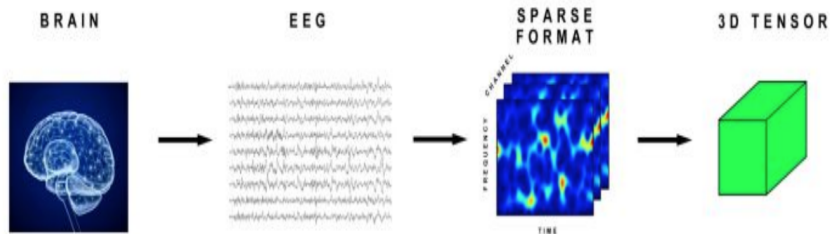


Hashtags



Other Examples

- ▶ Image Inpainting
- ▶ Video Inpainting
- ▶ Link Prediction
- ▶ EEG Data
- ▶ ...



Why some data is missing

- ▶ API restriction
- ▶ Error occurs when collecting the data
- ▶ Access restriction
- ▶ Sampling method
- ▶ Some of the data does not exist

Kronecker Product.

The Kronecker product of vectors $\mathbf{u} = [u_r] \in \mathbb{R}^{l_1}$ and $\mathbf{v} = [v_r] \in \mathbb{R}^{l_2}$ results in a vector $\mathbf{u} \otimes \mathbf{v} \in \mathbb{R}^{l_1 l_2}$ defined as

$$\mathbf{u} \otimes \mathbf{v} = \begin{bmatrix} u_1 \mathbf{v} \\ u_2 \mathbf{v} \\ \vdots \\ u_{l_1} \mathbf{v} \end{bmatrix}.$$

Khatri-Rao Product.

The Khatri-Rao product $U \odot V$ of two matrices $U = [u_{\ell,r}] \in \mathbb{R}^{l_1 \times R}$ and $V = [v_{\ell,r}] \in \mathbb{R}^{l_2 \times R}$ is

$$U \odot V = [u_{:,1} \otimes v_{:,1}, \dots, u_{:,R} \otimes v_{:,R}]$$

Tensor matricization.

Let $\mathcal{T} \in \mathbb{R}^{l_1 \times l_2 \times \dots \times l_k}$ is a k -th order tensor, the unfolded matrix is

$$\mathcal{T}_{(\ell)} \in \mathbb{R}^{l_\ell \times (l_1 \dots l_{\ell-1} l_{\ell+1} \dots l_k)}$$

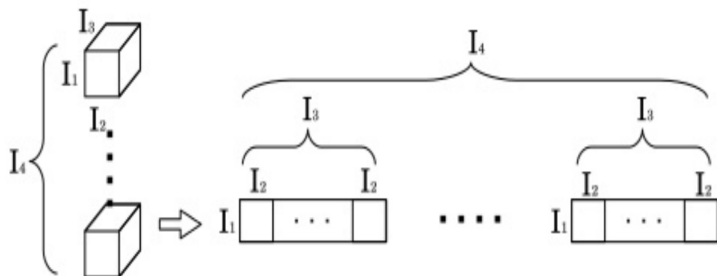
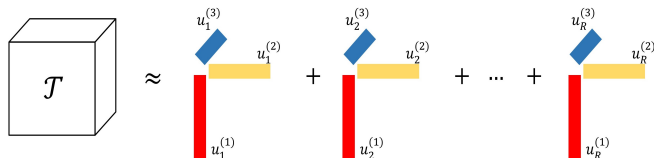


Figure : Unfolding Image

CP Decomposition



The CANDECOMP/PARAFAC (CP) model represents a tensor as a sum of rank-one tensors

$$T = \sum_{r=1}^R \mathbf{u}_r^{(1)} \circ \dots \circ \mathbf{u}_r^{(k)} = \llbracket U^{(1)}, \dots, U^{(k)} \rrbracket$$

Low Rank Tensor Completion (LRTC)

For a given tensor $\mathcal{T} \in \mathbb{R}^{I_1 \times \dots \times I_k}$, we want to find a low rank tensor \mathcal{Z} by solving the following optimization problem

$$\min_{\mathcal{Z}} \quad \frac{1}{2} \|\mathcal{P}_{\Omega}(\mathcal{T} - \mathcal{Z})\|_F^2 + \sum_{i=1}^k \lambda_i \|\mathcal{Z}_{(i)}\|_*$$

where \mathcal{P}_{Ω} is the projection operator that only retains those entries of the tensor that lie in the set Ω .

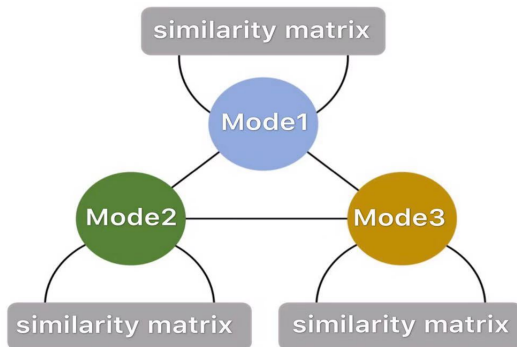
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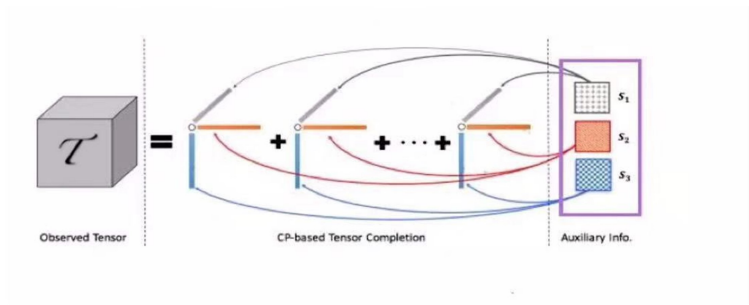
$$\min_{\mathcal{Z}} \quad \frac{1}{2} \|\mathcal{P}_{\Omega}(\mathcal{T} - \mathcal{Z})\|_F^2 + \sum_{i=1}^k \frac{\lambda_i}{2} \{ \|U^{(i)}\|_F^2 + \|(U^{(i)})^{\odot_{j \neq i}}\|_F^2 \}$$

where \mathcal{P}_{Ω} is the projection operator that only retains those entries of the tensor that lie in the set Ω .

Auxiliary Similarity



Our LRTC Model



$$\begin{aligned}
 \min_{U^{(1)}, \dots, U^{(k)}} f(U^{(1)}, \dots, U^{(k)}) &= \frac{1}{2} \|\mathcal{P}_\Omega(\mathcal{T} - \llbracket U^{(1)}, \dots, U^{(k)} \rrbracket)\|_F^2 \\
 &+ \sum_{i=1}^k \frac{\lambda_i}{2} \|U^{(i)}\|_F^2 + \sum_{i=1}^k \frac{\lambda_i}{2} \|(U^{(j)})^{\odot_{j \neq i}}\|_F^2 \\
 &+ \sum_{i=1}^k \frac{\lambda_L}{2} \left\langle U^{(i)} U^{(i)\top}, \mathbf{Lap}(U^{(i)}) \right\rangle.
 \end{aligned}$$

Algorithm 1 Altmin for solving LRTC

Initialization: $U_0^{(1)}, \dots, U_0^{(k)}$

1: **for** $p = 0, \dots, k$ **do**

2: **for** $i = 1 \dots, k$ **do**

3: $U_{p+1}^{(i)} = \operatorname{argminf}(U_{p+1}^{(1)}, \dots, U_{p+1}^{(i-1)}, U^{(i)}, U_p^{(i+1)}, \dots, U_p^{(k)})$

4: **end for**

5: **end for**

Compared with other algorithms, alternating minimization has several **advantages** for LRTC problem:

- ▶ It is easy to implement as there is no need to tune optimization parameters like step sizes.
- ▶ It converges very fast in practice.
- ▶ The objective function f is not convex with respect to variables $U^{(1)}, \dots, U^{(k)}$ together while the subproblem is easy to solve as it has a closed-form solution.
- ▶ Obviously, the objective function f is monotone decreasing.

Theorem

The iterates $\{U_p^{(1)}, \dots, U_p^{(k)}\}$ generated by Algorithm 1 from any initialization converges globally to a critical point of f .

Proof.

- ▶ f is a KL function with $\theta \in [1/2, 1)$
- ▶ Each subproblem is strongly convex.
- ▶ Notice f is coercive and real analytic, it is guaranteed to produce a bounded sequence.
- ▶ f is a \mathbf{C}^∞ function, thus ∇f is Lipschitz continuous on any bounded subset of domain.



Numerical Example

- ▶ Model advantage
 - Our model
 - Model without graph regularizer
 - Model without any regularizer
- ▶ Effectiveness of the proposed methods

- ▶ CPU time
- ▶ Reconstruction error (RE) = $\frac{\|\mathcal{T} - \llbracket U^{(1)}, U^{(2)}, U^{(3)} \rrbracket\|_F}{\|\mathcal{T}\|_F}$, where \mathcal{T} is the ground truth.
- ▶ Root mean squared error (RMSE) = $\frac{\|\mathcal{P}_{\Omega^c}(\mathcal{T} - \llbracket U^{(1)}, U^{(2)}, U^{(3)} \rrbracket)\|_F}{|\mathcal{P}_{\Omega^c}|^{1/2}}$, where \mathcal{P}_{Ω^c} denotes the unobserved projection and $|\mathcal{P}_{\Omega^c}|$ is the number in \mathcal{P}_{Ω^c} set.

Synthetic Data

- ▶ Randomly generate $U^{(i)} \in \mathbb{R}^{100 \times 10}$
- ▶ generate the graph Laplacian matrix $\mathbf{Lap}(U^{(1)}) \in \mathbb{R}^{100 \times 100}$ of $U^{(1)}$
- ▶ $\mathbf{Lap}(U^{(1)}) = V\Lambda V^\top$ by SVD

\mathcal{T} can be generated as follows

$$\mathcal{T}_{(1)} = V\Lambda^{-2}U^{(1)}(U^{(3)} \odot U^{(2)})^\top,$$

Method	SR=1%			SR=5%		
	GM	WGM	NM	GM	WGM	NM
Altmin-CG	0.2342	0.4395	$0.4006 \cdot 10$	$0.6611 \cdot 10^{-3}$	$0.6356 \cdot 10^{-3}$	$0.1098 \cdot 10^{-1}$
Altmin-ADMM	0.2484	0.3644	$0.1492 \cdot 10^2$	$0.6553 \cdot 10^{-3}$	$0.6375 \cdot 10^{-3}$	$0.1095 \cdot 10^{-1}$

TABLE 6.3

RE of the three models: GM 1 (with graph Laplacian), WGM (without graph Laplacian), NM (no regularizer).

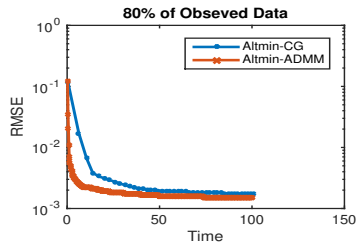
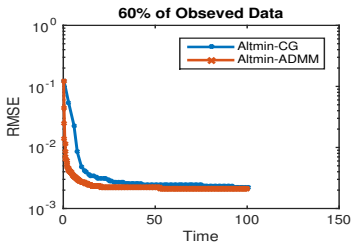
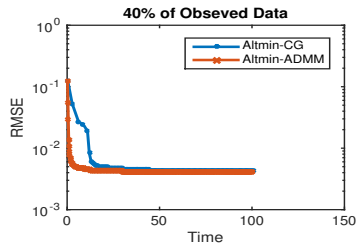
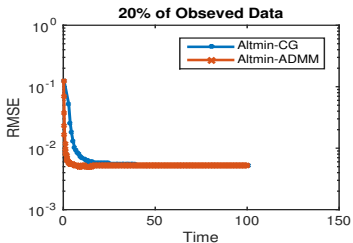
Flow Injection Analysis

- ▶ Rank-deficient spectral FIA dataset
- ▶ The represented tensor is of size $12(\textit{substances}) \times 100(\textit{wavelengths}) \times 89(\textit{reactiontimes})$.
- ▶ For 12 chemical substances, we build the similarity between two substances as the inverse of Euclidean distance between their feature vectors.
- ▶ For wavelengths and reaction times, the similar matrices are tridiagonal.

Method	SR=1%			SR=5%			SR=10%		
	GM	WGM	NM	GM	WGM	NM	GM	WGM	NM
Alt-CG	0.6469	0.8795	8.2624	0.0220	0.0326	3.9585	0.0135	0.0166	0.6746
Alt-ADMM	0.5752	0.7678	1.5776	0.0113	0.0113	0.1107	0.0140	0.0171	0.0380

TABLE 6.5

RE of the three models: GM 1 (with graph Laplacian), WGM (without graph Laplacian), NM (no regularizer).



Conclusion

- ▶ Low-rank tensor completion problem (LRTC) is to find a tensor with the minimum rank, which subjects to the equality constraints given by the observations.
- ▶ Graph Laplacian regularizer can help to improve the recovery quality when the missing ratio is high.
- ▶ Alternating minimization method is efficient to solve the LRTC problem.
- ▶ Our model achieve comparable error rates, while being significantly scalable.

Reference

[1] SONG, QINGQUAN AND GE, HANCHENG AND CAVERLEE, JAMES AND HU, XIA, *Tensor completion algorithms in big data analytics*, ACM Transactions on Knowledge Discovery from Data (TKDD), 13(1) (2019).

Questions?

Thank you!